#### Suppose you want to develop a data structure with:

- Insert(x): insert element x.
- Search(k): search for element with key k.
- **Delete**(x): delete element referenced by pointer x.
- find-by-rank( $\ell$ ): return the  $\ell$ -th element; return "error" if the data-structure contains less than \( \ell \) elements.



#### Suppose you want to develop a data structure with:

- Insert(x): insert element x.
- Search(k): search for element with key k.
- ▶ Delete(x): delete element referenced by pointer x.
- ▶ find-by-rank( $\ell$ ): return the  $\ell$ -th element; return "error" if the data-structure contains less than  $\ell$  elements.

Augment an existing data-structure instead of developing a new one.



- 1. choose an underlying data-structure
- determine additional information to be stored in the underlying structure
- verify/show how the additional information can be maintained for the basic modifying operations on the underlying structure.
- 4. develop the new operations



- 1. choose an underlying data-structure
- determine additional information to be stored in the underlying structure
- verify/show how the additional information can be maintained for the basic modifying operations on the underlying structure.
- **4.** develop the new operations



- choose an underlying data-structure
- determine additional information to be stored in the underlying structure
- 3. verify/show how the additional information can be maintained for the basic modifying operations on the underlying structure.
- 4. develop the new operations





- choose an underlying data-structure
- determine additional information to be stored in the underlying structure
- 3. verify/show how the additional information can be maintained for the basic modifying operations on the underlying structure.
- 4. develop the new operations



# Goal: Design a data-structure that supports insert, delete, search, and find-by-rank in time $O(\log n)$ .

- 1. We choose a red-black tree as the underlying data-structure.
- **2.** We store in each node v the size of the sub-tree rooted at v.
- 3. We need to be able to update the size-field in each node without asymptotically affecting the running time of insert, delete, and search. We come back to this step later...



Goal: Design a data-structure that supports insert, delete, search, and find-by-rank in time  $O(\log n)$ .

- 1. We choose a red-black tree as the underlying data-structure.
- 2. We store in each node v the size of the sub-tree rooted at v.
- 3. We need to be able to update the size-field in each node without asymptotically affecting the running time of insert, delete, and search. We come back to this step later...



Goal: Design a data-structure that supports insert, delete, search, and find-by-rank in time  $O(\log n)$ .

- 1. We choose a red-black tree as the underlying data-structure.
- 2. We store in each node v the size of the sub-tree rooted at v.
- 3. We need to be able to update the size-field in each node without asymptotically affecting the running time of insert, delete, and search. We come back to this step later...



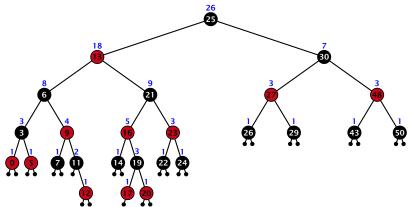
Goal: Design a data-structure that supports insert, delete, search, and find-by-rank in time  $O(\log n)$ .

4. How does find-by-rank work?
Find-by-rank(k) = Select(root,k) with

#### **Algorithm 7** Select(x, i)

- 1: **if** x = null **then return** error
- 2: **if** left[x]  $\neq$  null **then**  $r \leftarrow$  left[x]. size +1 **else**  $r \leftarrow 1$
- 3: if i = r then return x
- 4: if i < r then
- 5: **return** Select(left[x], i)
- 6: else
- 7: **return** Select(right[x], i r)

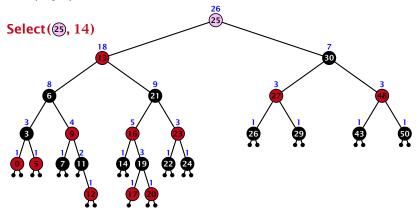




- decide whether you have to proceed into the left or right sub-tree
- adjust the rank that you are searching for if you go right



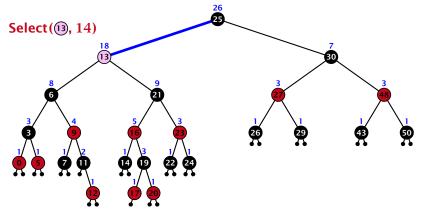




- decide whether you have to proceed into the left or right sub-tree
- adjust the rank that you are searching for if you go right



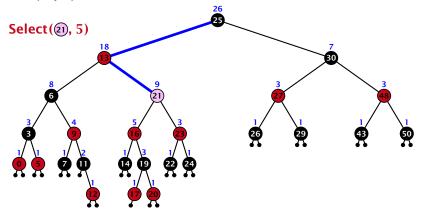




- decide whether you have to proceed into the left or right sub-tree
- adjust the rank that you are searching for if you go right



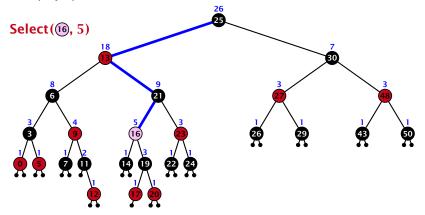




- decide whether you have to proceed into the left or right sub-tree
- adjust the rank that you are searching for if you go right



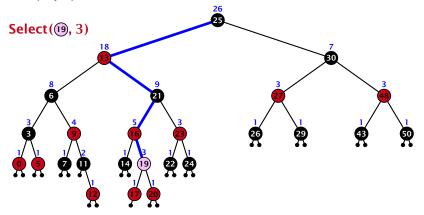




- decide whether you have to proceed into the left or right sub-tree
- adjust the rank that you are searching for if you go right



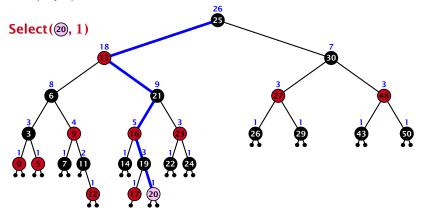




- decide whether you have to proceed into the left or right sub-tree
- adjust the rank that you are searching for if you go right







- decide whether you have to proceed into the left or right sub-tree
- adjust the rank that you are searching for if you go right





Goal: Design a data-structure that supports insert, delete, search, and find-by-rank in time  $O(\log n)$ .

3. How do we maintain information?

Search(k): Nothing to do.

**Insert**(x): When going down the search path increase the size field for each visited node. Maintain the size field during rotations.



Goal: Design a data-structure that supports insert, delete, search, and find-by-rank in time  $O(\log n)$ .

3. How do we maintain information?

Search(k): Nothing to do.

**Insert**(x): When going down the search path increase the size field for each visited node. Maintain the size field during rotations.



Goal: Design a data-structure that supports insert, delete, search, and find-by-rank in time  $O(\log n)$ .

3. How do we maintain information?

Search(k): Nothing to do.

Insert(x): When going down the search path increase the size field for each visited node. Maintain the size field during rotations.



Goal: Design a data-structure that supports insert, delete, search, and find-by-rank in time  $\mathcal{O}(\log n)$ .

3. How do we maintain information?

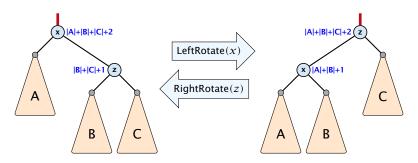
Search(k): Nothing to do.

Insert(x): When going down the search path increase the size field for each visited node. Maintain the size field during rotations.



#### **Rotations**

The only operation during the fix-up procedure that alters the tree and requires an update of the size-field:



The nodes x and z are the only nodes changing their size-fields.

The new size-fields can be computed locally from the size-fields of the children.

