## What do you measure?

- Memory requirement
- Running time
- Number of comparisons
- Number of multiplications
- Number of hard-disc accesses
- Program size
- Power consumption



### How do you measure?

- Implementing and testing on representative inputs
  - How do you choose your inputs?
  - May be very time-consuming.
  - Very reliable results if done correctly.
  - Results only hold for a specific machine and for a specific set of inputs.
- Theoretical analysis in a specific model of computation.
  - Gives asymptotic bounds like "this algorithm always runs in time  $\mathcal{O}(n^2)$ ".
  - Typically focuses on the worst case.
  - Can give lower bounds like "any comparison-based sorting algorithm needs at least Ω(n log n) comparisons in the worst case".



## Input length

The theoretical bounds are usually given by a function  $f : \mathbb{N} \to \mathbb{N}$  that maps the input length to the running time (or storage space, comparisons, multiplications, program size etc.).

The input length may e.g. be

- the size of the input (number of bits)
- the number of arguments

## Example 1

Suppose *n* numbers from the interval  $\{1, ..., N\}$  have to be sorted. In this case we usually say that the input length is *n* instead of e.g.  $n \log N$ , which would be the number of bits required to encode the input.



# **Model of Computation**

## How to measure performance

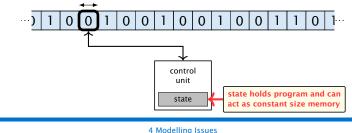
- Calculate running time and storage space etc. on a simplified, idealized model of computation, e.g. Random Access Machine (RAM), Turing Machine (TM), ...
- 2. Calculate number of certain basic operations: comparisons, multiplications, harddisc accesses, ...

Version 2. is often easier, but focusing on one type of operation makes it more difficult to obtain meaningful results.



# **Turing Machine**

- Very simple model of computation.
- Only the "current" memory location can be altered.
- Very good model for discussing computabiliy, or polynomial vs. exponential time.
- Some simple problems like recognizing whether input is of the form xx, where x is a string, have quadratic lower bound.
- $\Rightarrow$  Not a good model for developing efficient algorithms.

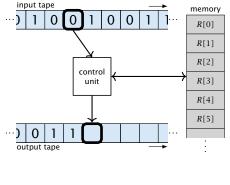


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## Random Access Machine (RAM)

- Input tape and output tape (sequences of zeros and ones; unbounded length).
- Memory unit: infinite but countable number of registers R[0], R[1], R[2], ....
- Registers hold integers.
- Indirect addressing.



Note that in the picture on the right the tapes are one-directional, and that a READ- or WRITE-operation always advances its tape.



4 Modelling Issues

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# Random Access Machine (RAM)

## Operations

• input operations (input tape  $\rightarrow R[i]$ )

▶ READ *i* 

• output operations ( $R[i] \rightarrow$  output tape)

▶ WRITE *i* 

- register-register transfers
  - $\blacktriangleright R[j] := R[i]$
  - $\blacktriangleright R[j] := 4$
- indirect addressing
  - $\blacktriangleright R[j] := R[R[i]]$

loads the content of the R[i]-th register into the *j*-th register

 $\blacktriangleright R[R[i]] := R[j]$ 

loads the content of the j-th into the R[i]-th register



# Random Access Machine (RAM)

## Operations

branching (including loops) based on comparisons

jump x jumps to position x in the program; sets instruction counter to x; reads the next operation to perform from register R[x]
jumpz x R[i] jump to x if R[i] = 0 if not the instruction counter is increased by 1;
jumpi i jump to R[i] (indirect jump);
arithmetic instructions: +, -, ×, /

```
R[i] := R[j] + R[k];
R[i] := -R[k];
```

The jump-directives are very close to the jump-instructions contained in the assembler language of real machines.



# **Model of Computation**

- uniform cost model
   Every operation takes time 1.
- logarithmic cost model

The cost depends on the content of memory cells:

- The time for a step is equal to the largest operand involved;
- The storage space of a register is equal to the length (in bits) of the largest value ever stored in it.

**Bounded word RAM model:** cost is uniform but the largest value stored in a register may not exceed  $2^w$ , where usually  $w = \log_2 n$ .

The latter model is quite realistic as the word-size of a standard computer that handles a problem of size n must be at least  $\log_2 n$  as otherwise the computer could either not store the problem instance or not address all its memory.



## Example 2

Algorithm 1 RepeatedSquaring(n) 1:  $r \leftarrow 2$ ; 2: for  $i = 1 \rightarrow n$  do 3:  $r \leftarrow r^2$ 4: return r

- running time (for Line 3):
  - uniform model: n steps
  - Iogarithmic model:

 $2 + 3 + 5 + \dots + (1 + 2^n) = 2^{n+1} - 1 + n = \Theta(2^n)$ 

- space requirement:
  - uniform model:  $\mathcal{O}(1)$
  - logarithmic model:  $\mathcal{O}(2^n)$



There are different types of complexity bounds:

best-case complexity:

 $C_{\rm bc}(n) := \min\{C(x) \mid |x| = n\}$ 

Usually easy to analyze, but not very meaningful.

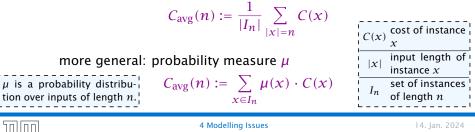
worst-case complexity:

```
C_{\rm wc}(n) := \max\{C(x) \mid |x| = n\}
```

Usually moderately easy to analyze; sometimes too pessimistic.

```
average case complexity:
```

larald Räcke



There are different types of complexity bounds:

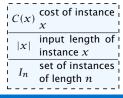
amortized complexity:

The average cost of data structure operations over a worst case sequence of operations.

randomized complexity:

The algorithm may use random bits. Expected running time (over all possible choices of random bits) for a fixed input x.

Then take the worst-case over all x with |x| = n.





 $\mu$  is a probability distribu-

tion over inputs of length n.

#### Bibliography

- [MS08] Kurt Mehlhorn, Peter Sanders: Algorithms and Data Structures — The Basic Toolbox, Springer, 2008
- [CLRS90] Thomas H. Cormen, Charles E. Leiserson, Ron L. Rivest, Clifford Stein: Introduction to algorithms (3rd ed.), McGraw-Hill, 2009

Chapter 2.1 and 2.2 of [MS08] and Chapter 2 of [CLRS90] are relevant for this section.

