How do we get an upper bound to a maximization LP?

max	13a	+	23 <i>b</i>	
s.t.	5 <i>a</i>	+	15 b	≤ 480
	4 <i>a</i>	+	4b	≤ 160
	35a	+	20 <i>b</i>	≤ 1190
			a, b	≥ 0

Note that a lower bound is easy to derive. Every choice of $a, b \ge 0$ gives us a lower bound (e.g. a = 12, b = 28 gives us a lower bound of 800).

If you take a conic combination of the rows (multiply the *i*-th row with $y_i \ge 0$) such that $\sum_i y_i a_{ij} \ge c_j$ then $\sum_i y_i b_i$ will be an upper bound.



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5.1 Weak Duality

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5.1 Weak Duality

Definition 2

Let $z = \max\{c^T x \mid Ax \le b, x \ge 0\}$ be a linear program P (called the primal linear program).

The linear program D defined by

$$w = \min\{b^T y \mid A^T y \ge c, y \ge 0\}$$

is called the dual problem.



Lemma 3 The dual of the dual problem is the primal problem.

Proof:

The dual problem is

[0] = 2 - 0.00 - 2 - 2.00 - 0.00 -



5.1 Weak Duality

Lemma 3

The dual of the dual problem is the primal problem.

Proof:

- $w = \min\{b^T y \mid A^T y \ge c, y \ge 0\}$
- $\blacktriangleright w = -\max\{-b^T y \mid -A^T y \le -c, y \ge 0\}$

- $|0| < \alpha_{\rm e} |0| < \alpha_{\rm e} |1| < \alpha_{\rm e}$



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The dual of the dual problem is the primal problem.

Proof:

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- $z = -\min\{-c^T x \mid -Ax \ge -b, x \ge 0\}$
 - $z = \max\{c^T x \mid Ax \le b, x \ge 0\}$



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$$z = -\min\{-c^T x \mid -Ax \ge -b, x \ge 0\}$$

$$z = \max\{c^T x \mid Ax \le b, x \ge 0\}$$



Let $z = \max\{c^T x \mid Ax \le b, x \ge 0\}$ and $w = \min\{b^T y \mid A^T y \ge c, y \ge 0\}$ be a primal dual pair.

x is primal feasible iff $x \in \{x \mid Ax \le b, x \ge 0\}$

y is dual feasible, iff $y \in \{y \mid A^T y \ge c, y \ge 0\}$.

Theorem 4 (Weak Duality)

Let \hat{x} be primal feasible and let \hat{y} be dual feasible. Then

 $c^T \hat{x} \leq z \leq w \leq b^T \hat{y} \; .$



5.1 Weak Duality

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Theorem 4 (Weak Duality)

Let \hat{x} be primal feasible and let \hat{y} be dual feasible. Then

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 $A^{T}\hat{\boldsymbol{y}} \ge \boldsymbol{c} \Rightarrow \hat{\boldsymbol{x}}^{T}A^{T}\hat{\boldsymbol{y}} \ge \hat{\boldsymbol{x}}^{T}\boldsymbol{c} \ (\hat{\boldsymbol{x}} \ge 0)$ $A\hat{\boldsymbol{x}} \le \boldsymbol{b} \Rightarrow \boldsymbol{y}^{T}A\hat{\boldsymbol{x}} \le \hat{\boldsymbol{y}}^{T}\boldsymbol{b} \ (\hat{\boldsymbol{y}} \ge 0)$ This choice

Since, there exists primal feasible \hat{x} with $c^T \hat{x} = z$, and dual feasible \hat{y} with $b^T \hat{y} = w$ we get $z \le w$.

If P is unbounded then D is infeasible.



5.1 Weak Duality

 $A^T \hat{\gamma} \ge c \Rightarrow \hat{x}^T A^T \hat{\gamma} \ge \hat{x}^T c \ (\hat{\chi} \ge 0)$

This gives

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5.1 Weak Duality

 $A^T \hat{y} \ge c \Rightarrow \hat{x}^T A^T \hat{y} \ge \hat{x}^T c \ (\hat{x} \ge 0)$

 $A\hat{x} \le b \Rightarrow y^T A\hat{x} \le \hat{y}^T b \ (\hat{y} \ge 0)$

This gives

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5.1 Weak Duality

 $A^{T}\hat{y} \ge c \Rightarrow \hat{x}^{T}A^{T}\hat{y} \ge \hat{x}^{T}c \ (\hat{x} \ge 0)$ $A\hat{x} \le b \Rightarrow y^{T}A\hat{x} \le \hat{y}^{T}b \ (\hat{y} \ge 0)$

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5.1 Weak Duality

$$\begin{aligned} A^T \hat{y} &\geq c \Rightarrow \hat{x}^T A^T \hat{y} \geq \hat{x}^T c \ (\hat{x} \geq 0) \\ A \hat{x} &\leq b \Rightarrow y^T A \hat{x} \leq \hat{y}^T b \ (\hat{y} \geq 0) \end{aligned}$$

This gives

$$c^T \hat{x} \leq \hat{y}^T A \hat{x} \leq b^T \hat{y} \ .$$

Since, there exists primal feasible \hat{x} with $c^T \hat{x} = z$, and dual feasible \hat{y} with $b^T \hat{y} = w$ we get $z \le w$.

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$$c^T \hat{x} \leq \hat{y}^T A \hat{x} \leq b^T \hat{y} \ .$$

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If P is unbounded then D is infeasible.



5.2 Simplex and Duality

The following linear programs form a primal dual pair:

$$z = \max\{c^T x \mid Ax = b, x \ge 0\}$$
$$w = \min\{b^T y \mid A^T y \ge c\}$$

This means for computing the dual of a standard form LP, we do not have non-negativity constraints for the dual variables.



Primal:

 $\max\{c^T x \mid Ax = b, x \ge 0\}$



Primal:

$$\max\{c^T x \mid Ax = b, x \ge 0\}$$
$$= \max\{c^T x \mid Ax \le b, -Ax \le -b, x \ge 0\}$$



Primal:

$$\max\{c^{T}x \mid Ax = b, x \ge 0\}$$

= $\max\{c^{T}x \mid Ax \le b, -Ax \le -b, x \ge 0\}$
= $\max\{c^{T}x \mid \begin{bmatrix} A \\ -A \end{bmatrix} x \le \begin{bmatrix} b \\ -b \end{bmatrix}, x \ge 0\}$



Primal:

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= $\max\{c^{T}x \mid Ax \le b, -Ax \le -b, x \ge 0\}$
= $\max\{c^{T}x \mid \begin{bmatrix} A \\ -A \end{bmatrix} x \le \begin{bmatrix} b \\ -b \end{bmatrix}, x \ge 0\}$

Dual:

$$\min\{[b^T - b^T]y \mid [A^T - A^T]y \ge c, y \ge 0\}$$



Primal:

$$\max\{c^{T}x \mid Ax = b, x \ge 0\}$$

= $\max\{c^{T}x \mid Ax \le b, -Ax \le -b, x \ge 0\}$
= $\max\{c^{T}x \mid \begin{bmatrix} A \\ -A \end{bmatrix} x \le \begin{bmatrix} b \\ -b \end{bmatrix}, x \ge 0\}$

Dual:

$$\min\{\begin{bmatrix} b^T & -b^T \end{bmatrix} y \mid \begin{bmatrix} A^T & -A^T \end{bmatrix} y \ge c, y \ge 0\}$$
$$= \min\left\{\begin{bmatrix} b^T & -b^T \end{bmatrix} \cdot \begin{bmatrix} y^+ \\ y^- \end{bmatrix} \mid \begin{bmatrix} A^T & -A^T \end{bmatrix} \cdot \begin{bmatrix} y^+ \\ y^- \end{bmatrix} \ge c, y^- \ge 0, y^+ \ge 0\right\}$$



5.2 Simplex and Duality

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Dual:

$$\min\{\begin{bmatrix} b^T & -b^T \end{bmatrix} y \mid \begin{bmatrix} A^T & -A^T \end{bmatrix} y \ge c, y \ge 0\}$$

=
$$\min\left\{\begin{bmatrix} b^T & -b^T \end{bmatrix} \cdot \begin{bmatrix} y^+ \\ y^- \end{bmatrix} \mid \begin{bmatrix} A^T & -A^T \end{bmatrix} \cdot \begin{bmatrix} y^+ \\ y^- \end{bmatrix} \ge c, y^- \ge 0, y^+ \ge 0\right\}$$

=
$$\min\left\{b^T \cdot (y^+ - y^-) \mid A^T \cdot (y^+ - y^-) \ge c, y^- \ge 0, y^+ \ge 0\right\}$$



Primal:

$$\max\{c^{T}x \mid Ax = b, x \ge 0\}$$

=
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=
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=
$$\min\left\{b^T y' \mid A^T y' \ge c\right\}$$



Suppose that we have a basic feasible solution with reduced cost

 $\tilde{c} = c^T - c_B^T A_B^{-1} A \le 0$

This is equivalent to $A^T (A_B^{-1})^T c_B \ge c$

 $y^* = (A_B^{-1})^T c_B$ is solution to the dual $\min\{b^T y | A^T y \ge c\}$.

Hence, the solution is optimal.



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Hence, the solution is optimal.



Proof of Optimality Criterion for Simplex

Suppose that we have a basic feasible solution with reduced cost

 $\tilde{c} = c^T - c_B^T A_B^{-1} A \le 0$

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 $y^{*} = (A_{B}^{-1})^{T} c_{B} \text{ is solution to the dual } \min\{b^{T} y | A^{T} y \ge c\}.$ $b^{T} y^{*} = (A x^{*})^{T} y^{*} = (A_{B} x^{*}_{B})^{T} y^{*}$ $= (A_{B} x^{*}_{B})^{T} (A^{-1}_{B})^{T} c_{B} = (x^{*}_{B})^{T} A^{T}_{B} (A^{-1}_{B})^{T} c_{B}$ $= c^{T} x^{*}$

Hence, the solution is optimal.



16. Apr. 2024 21/53

5.3 Strong Duality

 $P = \max\{c^T x \mid Ax \le b, x \ge 0\}$

 n_A : number of variables, m_A : number of constraints

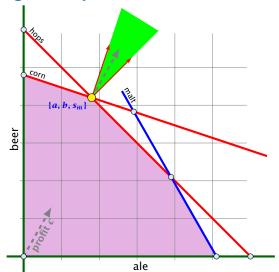
We can put the non-negativity constraints into A (which gives us unrestricted variables): $\bar{P} = \max\{c^T x \mid \bar{A}x \leq \bar{b}\}$

 $n_{ar{A}}=n_A$, $m_{ar{A}}=m_A+n_A$

Dual
$$D = \min\{\bar{b}^T y \mid \bar{A}^T y = c, y \ge 0\}.$$



5.3 Strong Duality



The profit vector c lies in the cone generated by the normals for the hops and the corn constraint (the tight constraints).

Strong Duality

Theorem 5 (Strong Duality)

Let P and D be a primal dual pair of linear programs, and let z^* and w^* denote the optimal solution to P and D, respectively. Then

 $z^* = w^*$



Lemma 6 (Weierstrass)

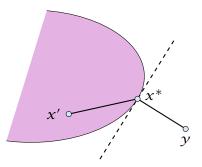
Let X be a compact set and let f(x) be a continuous function on X. Then $\min\{f(x) : x \in X\}$ exists.

(without proof)



Lemma 7 (Projection Lemma)

Let $X \subseteq \mathbb{R}^m$ be a non-empty convex set, and let $y \notin X$. Then there exist $x^* \in X$ with minimum distance from y. Moreover for all $x \in X$ we have $(y - x^*)^T (x - x^*) \le 0$.



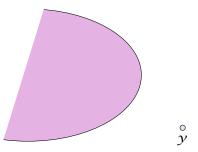


16. Apr. 2024 26/53

• Define f(x) = ||y - x||.

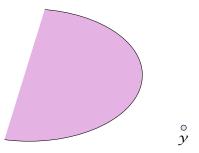
We want to apply Weierstrass but X may not be bounded.

- $X \neq \emptyset$. Hence, there exists $x' \in X$.
- ▶ Define $X' = \{x \in X \mid ||y x|| \le ||y x'||\}$. This set is closed and bounded.
- Applying Weierstrass gives the existence.



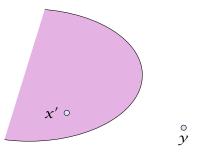


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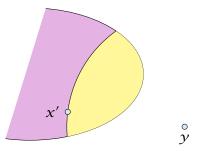


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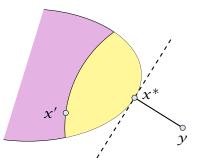


- Define f(x) = ||y x||.
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- Applying Weierstrass gives the existence.





5.3 Strong Duality

16. Apr. 2024 27/53



 x^* is minimum. Hence $\|y - x^*\|^2 \le \|y - x\|^2$ for all $x \in X$.



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By convexity: $x \in X$ then $x^* + \epsilon(x - x^*) \in X$ for all $0 \le \epsilon \le 1$.



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 $\|y - x^*\|^2$



 x^* is minimum. Hence $\|y - x^*\|^2 \le \|y - x\|^2$ for all $x \in X$.

By convexity: $x \in X$ then $x^* + \epsilon(x - x^*) \in X$ for all $0 \le \epsilon \le 1$.

$$\|y - x^*\|^2 \le \|y - x^* - \epsilon(x - x^*)\|^2$$



 x^* is minimum. Hence $\|y - x^*\|^2 \le \|y - x\|^2$ for all $x \in X$.

By convexity: $x \in X$ then $x^* + \epsilon(x - x^*) \in X$ for all $0 \le \epsilon \le 1$.

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Letting $\epsilon \rightarrow 0$ gives the result.



16. Apr. 2024 28/53

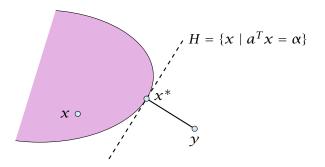
Theorem 8 (Separating Hyperplane)

Let $X \subseteq \mathbb{R}^m$ be a non-empty closed convex set, and let $y \notin X$. Then there exists a separating hyperplane $\{x \in \mathbb{R} : a^T x = \alpha\}$ where $a \in \mathbb{R}^m$, $\alpha \in \mathbb{R}$ that separates y from X. $(a^T y < \alpha; a^T x \ge \alpha$ for all $x \in X$)



• Let $x^* \in X$ be closest point to y in X.

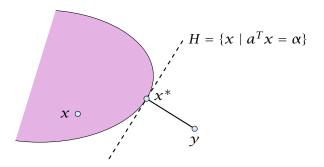
- By previous lemma $(y x^*)^T (x x^*) \le 0$ for all $x \in X$.
- Choose $a = (x^* y)$ and $\alpha = a^T x^*$.
- For $x \in X$: $a^T(x x^*) \ge 0$, and, hence, $a^T x \ge \alpha$.
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16. Apr. 2024 **30/53**

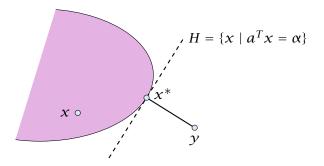
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16. Apr. 2024 **30/53**

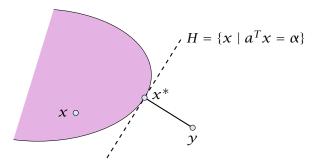
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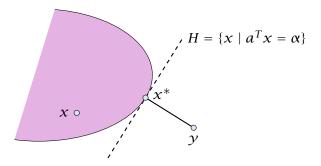




5.3 Strong Duality

16. Apr. 2024 **30/53**

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5.3 Strong Duality

16. Apr. 2024 30/53

Lemma 9 (Farkas Lemma)

Let A be an $m \times n$ matrix, $b \in \mathbb{R}^m$. Then exactly one of the following statements holds.

- **1.** $\exists x \in \mathbb{R}^n$ with Ax = b, $x \ge 0$
- **2.** $\exists y \in \mathbb{R}^m$ with $A^T y \ge 0$, $b^T y < 0$

Assume \hat{x} satisfies 1. and \hat{y} satisfies 2. Then

 $0 > y^T b = y^T A x \ge 0$

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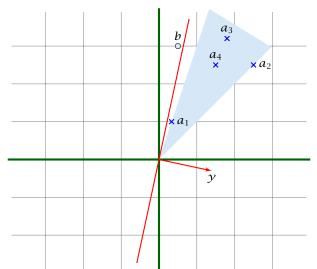
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Farkas Lemma



If b is not in the cone generated by the columns of A, there exists a hyperplane y that separates b from the cone.

Now, assume that 1. does not hold.

Consider $S = \{Ax : x \ge 0\}$ so that *S* closed, convex, $b \notin S$.

We want to show that there is y with $A^T y \ge 0$, $b^T y < 0$.

Let γ be a hyperplane that separates b from S. Hence, $\gamma^T b < \alpha$ and $\gamma^T s \ge \alpha$ for all $s \in S$.

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Proof of Farkas Lemma

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 $y^T A x \ge \alpha$ for all $x \ge 0$. Hence, $y^T A \ge 0$ as we can choose x arbitrarily large.

Lemma 10 (Farkas Lemma; different version)

Let A be an $m \times n$ matrix, $b \in \mathbb{R}^m$. Then exactly one of the following statements holds.

- **1.** $\exists x \in \mathbb{R}^n$ with $Ax \le b$, $x \ge 0$
- **2.** $\exists y \in \mathbb{R}^m$ with $A^T y \ge 0$, $b^T y < 0$, $y \ge 0$

Rewrite the conditions:
1.
$$\exists x \in \mathbb{R}^n$$
 with $\begin{bmatrix} A & I \end{bmatrix} \cdot \begin{bmatrix} x \\ s \end{bmatrix} = b, x \ge 0, s \ge 0$
2. $\exists y \in \mathbb{R}^m$ with $\begin{bmatrix} A^T \\ I \end{bmatrix} y \ge 0, b^T y < 0$



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$$P: z = \max\{c^T x \mid Ax \le b, x \ge 0\}$$

$$D: w = \min\{b^T y \mid A^T y \ge c, y \ge 0\}$$

Theorem 11 (Strong Duality)

Let P and D be a primal dual pair of linear programs, and let z and w denote the optimal solution to P and D, respectively (i.e., P and D are non-empty). Then

z = w .





 $z \leq w$: follows from weak duality



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- $z \ge w$:



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- We show $z < \alpha$ implies $w < \alpha$.



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$\exists x \in \mathbb{R}^n$			
s.t.	Ax	\leq	b
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	x	\geq	0



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We show $z < \alpha$ implies $w < \alpha$.

$\exists x \in \mathbb{R}^n$				$\exists y \in \mathbb{R}^m; v \in \mathbb{R}$
s.t.	Ax	\leq	b	s.t. $A^T y - cv \ge 0$
	$-c^T x$	\leq	$-\alpha$	$b^T y - \alpha v < 0$
	x	≥	0	$y, v \geq 0$



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$x \ge 0$	$y, v \geq 0$

From the definition of α we know that the first system is infeasible; hence the second must be feasible.



$$\exists y \in \mathbb{R}^{m}; v \in \mathbb{R}$$

s.t. $A^{T}y - cv \geq 0$
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If the solution y, v has v = 0 we have that

$$\exists y \in \mathbb{R}^m$$

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is feasible. By Farkas lemma this gives that LP P is infeasible. Contradiction to the assumption of the lemma.



- Hence, there exists a solution y, v with v > 0.
- We can rescale this solution (scaling both y and v) s.t. v = 1.
- Then y is feasible for the dual but $b^T y < \alpha$. This means that $w < \alpha$.



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Definition 12 (Linear Programming Problem (LP))

Let $A \in \mathbb{Q}^{m \times n}$, $b \in \mathbb{Q}^m$, $c \in \mathbb{Q}^n$, $\alpha \in \mathbb{Q}$. Does there exist $x \in \mathbb{Q}^n$ s.t. Ax = b, $x \ge 0$, $c^T x \ge \alpha$?

Questions:

- Is LP in NP?
- Is LP in co-NP? yes!
- Is LP in P?

Proof:

- Given a primal maximization problem () and a parameter Suppose that 0 < 0.00 () 0 < 0.00
- We can prove this by providing an optimal basis for the duality
- A verifier can check that the associated dual solution fulfills



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Complementary Slackness

Lemma 13

Assume a linear program $P = \max\{c^T x \mid Ax \le b; x \ge 0\}$ has solution x^* and its dual $D = \min\{b^T y \mid A^T y \ge c; y \ge 0\}$ has solution y^* .

- **1.** If $x_i^* > 0$ then the *j*-th constraint in *D* is tight.
- **2.** If the *j*-th constraint in *D* is not tight than $x_i^* = 0$.
- **3.** If $y_i^* > 0$ then the *i*-th constraint in *P* is tight.
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- **4.** If the *i*-th constraint in *P* is not tight than $y_i^* = 0$.

If we say that a variable x_j^* (y_i^*) has slack if $x_j^* > 0$ ($y_i^* > 0$), (i.e., the corresponding variable restriction is not tight) and a contraint has slack if it is not tight, then the above says that for a primal-dual solution pair it is not possible that a constraint **and** its corresponding (dual) variable has slack.



Proof: Complementary Slackness

Analogous to the proof of weak duality we obtain

 $c^T x^* \leq y^{*T} A x^* \leq b^T y^*$



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This gives e.g.

$$\sum_{j} (\mathcal{Y}^{T} A - c^{T})_{j} \mathbf{x}_{j}^{*} = 0$$



5.4 Interpretation of Dual Variables

16. Apr. 2024 41/53

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From the constraint of the dual it follows that $y^T A \ge c^T$. Hence the left hand side is a sum over the product of non-negative numbers. Hence, if e.g. $(y^T A - c^T)_j > 0$ (the *j*-th constraint in the dual is not tight) then $x_j = 0$ (2.). The result for (1./3./4.) follows similarly.



Brewer: find mix of ale and beer that maximizes profits

Entrepeneur: buy resources from brewer at minimum cost C, H, M: unit price for corn, hops and malt.

Note that brewer won't sell (at least not all) if e.g. 5C + 4H + 35M < 13 as then brewing ale would be advantageous.

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 $\max 13a + 23b$ s.t. $5a + 15b \le 480$ $4a + 4b \le 160$ $35a + 20b \le 1190$ $a, b \ge 0$

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min	480 <i>C</i>	+	160H	+	1190M	
s.t.	5 <i>C</i>	+	4H	+	35 <i>M</i>	≥ 13
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Marginal Price:

- How much money is the brewer willing to pay for additional amount of Corn, Hops, or Malt?
- ▶ We are interested in the marginal price, i.e., what happens if we increase the amount of Corn, Hops, and Malt by ε_C , ε_H , and ε_M , respectively.
- The profit increases to $\max\{c^T x \mid Ax \le b + \varepsilon; x \ge 0\}$. Because of strong duality this is equal to

$$\begin{array}{rcl} \min & (b^T + \epsilon^T) y \\ \text{s.t.} & A^T y &\geq c \\ & y &\geq 0 \end{array}$$



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16. Apr. 2024 43/53

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$$\begin{array}{lll} \min & (b^T + \epsilon^T)y \\ \text{s.t.} & A^Ty \geq c \\ & y \geq 0 \end{array}$$



If ϵ is "small" enough then the optimum dual solution γ^* might not change. Therefore the profit increases by $\sum_i \epsilon_i \gamma_i^*$.

Therefore we can interpret the dual variables as marginal prices.

Note that with this interpretation, complementary slackness becomes obvious.

- If the brewer has slack of some resource (e.g. com) then he is not willing to pay anything for it (corresponding dual variable is zero).
- If the dual variable for some resource is non-zero, then an increase of this resource increases the profit of the brewer. Hence, it makes no sense to have left-overs of this resource. Therefore its slack must be zero.



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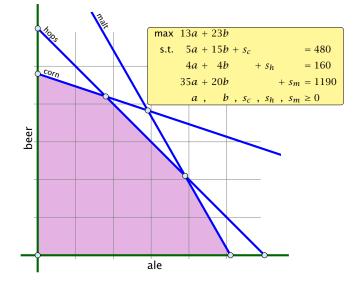
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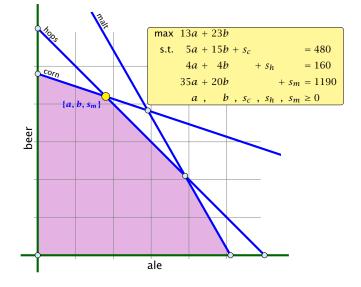
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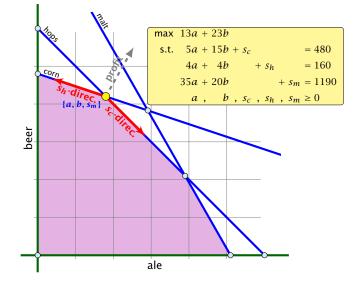
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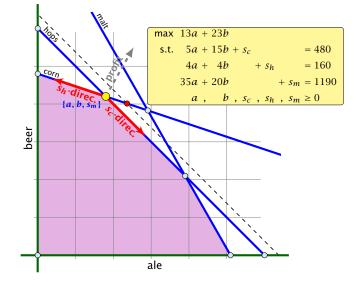
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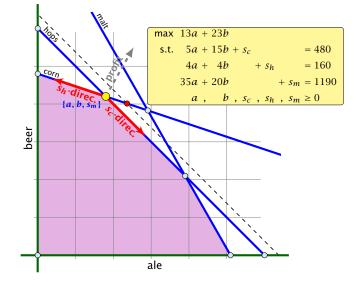


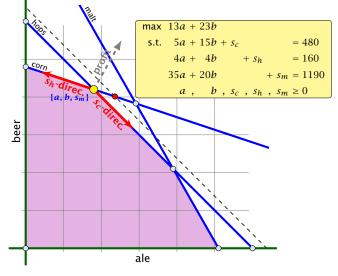




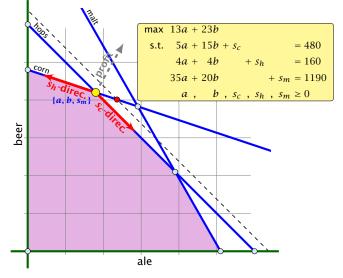








The change in profit when increasing hops by one unit is $= c_B^T A_B^{-1} e_h$.



The change in profit when increasing hops by one unit is

$$=\underbrace{c_B^T A_B^{-1}}_{\mathcal{Y}^*} e_h.$$

Of course, the previous argument about the increase in the primal objective only holds for the non-degenerate case.

If the optimum basis is degenerate then increasing the supply of one resource may not allow the objective value to increase.



Definition 14

An (s, t)-flow in a (complete) directed graph $G = (V, V \times V, c)$ is a function $f : V \times V \mapsto \mathbb{R}_0^+$ that satisfies

1. For each edge (x, y)

 $0 \leq f_{xy} \leq c_{xy}$.

(capacity constraints)

2. For each $v \in V \setminus \{s, t\}$

$$\sum_{x} f_{vx} = \sum_{x} f_{xv} \; .$$

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16. Apr. 2024 47/53

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Definition 15 The value of an (s,t)-flow f is defined as

$$\operatorname{val}(f) = \sum_{X} f_{SX} - \sum_{X} f_{XS} .$$

Maximum Flow Problem: Find an (s,t)-flow with maximum value.



5.5 Computing Duals

16. Apr. 2024 48/53

Definition 15 The value of an (s, t)-flow f is defined as

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Maximum Flow Problem:

Find an (s, t)-flow with maximum value.



max		$\sum_{z} f_{sz} - \sum_{z} f_{zs}$			
s.t.	$\forall (z, w) \in V \times V$	f_{zw}	\leq	C_{ZW}	ℓ_{zw}
	$\forall w \neq s, t$	$\sum_{z} f_{zw} - \sum_{z} f_{wz}$			
		f_{zw}	\geq	0	



max		$\sum_{z} f_{sz} - \sum_{z} f_{zs}$			
s.t.	$\forall (z, w) \in V \times V$	f_{zw}	\leq	C_{ZW}	ℓ_{zw}
	$\forall w \neq s, t$	$\sum_{z} f_{zw} - \sum_{z} f_{wz}$	=	0	p_w
		f_{zw}	\geq	0	

min		$\sum_{(xy)} c_{xy} \ell_{xy}$		
s.t.	$f_{xy}(x, y \neq s, t)$:	$1\ell_{xy}-1p_x+1p_y$	\geq	0
	$f_{sy}(y \neq s,t)$:	$1\ell_{sy}$ $+1p_y$	\geq	1
	$f_{xs} (x \neq s, t)$:	$1\ell_{xs}-1p_x$	\geq	-1
	$f_{ty}(y \neq s,t)$:	$1\ell_{ty}$ $+1p_y$	\geq	0
	$f_{xt} (x \neq s, t)$:	$1\ell_{xt}-1p_x$	\geq	0
	f_{st} :	$1\ell_{st}$	\geq	1
	f_{ts} :	$1\ell_{ts}$	\geq	-1
		ℓ_{xy}	≥	0



5.5 Computing Duals



5.5 Computing Duals

16. Apr. 2024 50/53

with $p_t = 0$ and $p_s = 1$.



16. Apr. 2024 51/53

min		$\sum_{(xy)} c_{xy} \ell_{xy}$		
s.t.	f_{xy} :	$1\ell_{xy}-1p_x+1p_y$	\geq	0
		ℓ_{xy}	\geq	0
		p_s	=	1
		p_t	=	0

We can interpret the ℓ_{xy} value as assigning a length to every edge.

The value p_x for a variable, then can be seen as the distance of x to t (where the distance from s to t is required to be 1 since $p_s = 1$).

The constraint $p_x \leq \ell_{xy} + p_y$ then simply follows from triangle inequality $(d(x,t) \leq d(x,y) + d(y,t) \Rightarrow d(x,t) \leq \ell_{xy} + d(y,t))$.



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16. Apr. 2024 52/53

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One can show that there is an optimum LP-solution for the dual problem that gives an integral assignment of variables.

This means $p_x = 1$ or $p_x = 0$ for our case. This gives rise to a cut in the graph with vertices having value 1 on one side and the other vertices on the other side. The objective function then evaluates the capacity of this cut.

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